# **Decoupled Coverage Anti-Aliasing**

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#### Motivation

- Geometric anti-aliasing is a long standing problem
- MSAA as gold standard
  - Idea: decoupled shading and visibility
  - Reduce shading cost
- For high quality rendering, storage is costly

Feature Film



Source: DICE



#### Motivation



#### Estimate:

- > 4 byte/sample color
- > 4 byte/sample depth
- No compression
- Linear growth with # samples
- >64x MSAA 1080p:
  - ~1 GB for RGBA8
  - 2+ GB for G-Buffer

### **Related Work**

- Simple/Complex [Lauritzen 2010]
  - Analyze planar features shared in G-Buffer
  - Amortize shading cost
  - Large memory footprint with sizeable depth and color information





### **Related Work**

- Surface Based AA (SBAA)[Salvi & Vidimče 2012], Streaming G-Buffer [Kerzner & Salvi 2014]
  - Only store N important surfaces
- Aggregate Geometry AA (AGAA) [Crassin et al. 2015]
  - Filter & compression

 Rely on MSAA depth sampling -> large memory footprint @ high sample rates



Source: [Salvi & Vidimče 2012]



Source: [Crassin et al. 2015]

#### Motivation

- Observations from prior G-Buffer compression work [Salvi & Vidimče 2012]
  - 2-3 shading surfaces are enough for each pixel
- Can we use a higher fidelity coverage for compressed surfaces?
  - High fidelity coverage mask easy to get [Waller et al. 2000] [Wyman et al. 2015]
  - Model contribution of each surface more precisely
- Or, in other words...
  - Can we decouple coverage from visibility?

UCSB

Higher anti-aliasing quality in less storage by decoupling coverage and visibility rates

























#### Decoupled Coverage AA



#### Decoupled Coverage AA



#### Decoupled Coverage AA



#### Decoupled Coverage AA

**HPG 2015** 



Surface List



#### Decoupled Coverage AA

**HPG 2015** 





High Quality Coverage Mask





#### Decoupled Coverage AA



![](_page_15_Picture_4.jpeg)

- MSAA: <= 8 sample/pixel
  - Depth + colors replicated per sample (e.g., 8 bytes/sample RGBA8 and 16-20 bytes/sample deferred)

- Coverage mask is cheaper than MSAA sample (depth+coverage)
  - 1 coverage sample -> 1 bit
  - High sampling rate supported

![](_page_16_Picture_6.jpeg)

Projection

![](_page_17_Figure_2.jpeg)

![](_page_17_Figure_3.jpeg)

Coverage Mask

![](_page_17_Picture_5.jpeg)

![](_page_17_Picture_6.jpeg)

![](_page_17_Picture_7.jpeg)

![](_page_18_Figure_1.jpeg)

![](_page_18_Figure_2.jpeg)

![](_page_18_Picture_3.jpeg)

![](_page_18_Picture_4.jpeg)

![](_page_18_Picture_5.jpeg)

![](_page_19_Figure_1.jpeg)

Look-up table for per-edge coverage

![](_page_19_Picture_3.jpeg)

![](_page_19_Picture_4.jpeg)

![](_page_20_Figure_1.jpeg)

• Look-up table for per-edge coverage

![](_page_20_Picture_3.jpeg)

![](_page_20_Picture_4.jpeg)

### **Fragment Merging**

- Try to merge fragment into existing shading surfaces
  - Satisfy merge rules
  - Combine the coverage mask
  - Weighted average normal, depth, etc., based on coverage bits
  - Fail: add fragment into list
- Aggregates geometry information
- Without losing high fidelity coverage information

![](_page_21_Picture_8.jpeg)

### Merge heuristics

- Merge rules
  - Aligned normal

![](_page_22_Picture_3.jpeg)

• Overlapping depth intervals

![](_page_22_Picture_5.jpeg)

![](_page_22_Picture_6.jpeg)

### **Fragment Merging**

- Keep 4 surfaces at most
  - 2-3 surfaces for Streaming G-Buffer [Kerzner & Salvi 2014]
  - 2 surfaces for AGAA [Crassin et al. 2015]
- Sufficient to handle sophisticated scenes
  - High fidelity coverage mask catches small geometry
  - Discard rules vs. Clustering approach

![](_page_23_Picture_7.jpeg)

- When the surface list is full, we need to discard
  - Discard the one with smallest visible coverage
- Discard loses information...
  - Leaking to background

Blue as background color

![](_page_24_Picture_6.jpeg)

Only merge once

Reference

![](_page_24_Picture_9.jpeg)

- How does the leaking happen with single merge?
- Consider this complex pixel:
  - The eye should see only the blue surfaces
  - Consider this primitive order
  - Large derivatives result in big bounding box
  - No accurate coverage determination...
  - But only have room for 4 surfaces

![](_page_25_Picture_8.jpeg)

![](_page_25_Picture_9.jpeg)

• How does the leaking happen with single merge?

- Discarding small, nearby surfaces likely to cause leaks
- Prefer to avoid discarding important geometry
  - Prevent loss of nearby sub-pixel geometry
  - Potential cost of blurring color on small surfaces

![](_page_26_Picture_6.jpeg)

![](_page_26_Picture_7.jpeg)

![](_page_26_Picture_8.jpeg)

- Give the smallest surface a second chance!
- Merge before discard:
  - Select the smallest coverage surface after first merge
    - Never try discard the front most one
  - Try to merge it with others using relaxed rule
    - Apply only overlapping depth interval rule
    - If mergeable, average all attributes as usual

![](_page_27_Figure_8.jpeg)

(a)

(b)

![](_page_27_Picture_9.jpeg)

#### Implementation

- Conservative rasterizer
  - Process partially covered fragments

- Pixel shader interlock
  - Ensure primitive ordering
  - Fragment shader lock
  - Resolve discard & temporal artifact

#### • Z-prepass

![](_page_28_Picture_8.jpeg)

#### Results

![](_page_29_Picture_1.jpeg)

![](_page_29_Picture_2.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_30_Picture_1.jpeg)

![](_page_30_Picture_2.jpeg)

![](_page_31_Picture_0.jpeg)

![](_page_31_Picture_1.jpeg)

![](_page_31_Picture_2.jpeg)

![](_page_31_Picture_3.jpeg)

![](_page_32_Picture_0.jpeg)

![](_page_32_Picture_1.jpeg)

![](_page_32_Picture_2.jpeg)

![](_page_32_Picture_3.jpeg)

![](_page_33_Picture_0.jpeg)

#### 512x Supersampling

![](_page_34_Picture_1.jpeg)

![](_page_35_Picture_0.jpeg)

![](_page_36_Picture_0.jpeg)

![](_page_37_Picture_0.jpeg)

![](_page_38_Picture_0.jpeg)

## 512x Supersampling

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![](_page_39_Picture_1.jpeg)

4S DCAA

![](_page_39_Picture_2.jpeg)

![](_page_40_Picture_0.jpeg)

![](_page_41_Picture_0.jpeg)

fil les

![](_page_42_Picture_0.jpeg)

![](_page_43_Picture_0.jpeg)

4S SBAA

#### **4S DCAA**

![](_page_44_Picture_1.jpeg)

#### 512x Supersampling

![](_page_45_Figure_1.jpeg)

### Evaluation

![](_page_46_Figure_1.jpeg)

- 28 bytes/surface × 4 surfaces/pixel = 112 bytes/pixel
- 8x MSAA: 16 bytes/sample  $\times$  8 = 128 bytes/pixel (1.14x of DCAA)
- 64x SuperSampling: 16 bytes/sample × 64 = 1024 bytes/pixel (9.14x of DCAA)

![](_page_46_Picture_5.jpeg)

![](_page_47_Figure_0.jpeg)

	Z-Prepass	Merge	Resolve & Render	Total	MSE		
					4S SBAA	8x MSAA	DCAA
Citadel	1.3 ms	23.2 ms	6.4 ms	30.9 ms	2.47*10-4	1.32*10 <sup>-4</sup>	<b>6.40*10</b> <sup>-5</sup>
Tentacles	1.3 ms	574.5 ms	6.2 ms	582.0 ms	2.28*10 <sup>-3</sup>	6.05*10 <sup>-4</sup>	<b>5.65*10</b> <sup>-4</sup>

Υ**Π** 

#### Limitation

- Rendering speed
  - Pixel Shader Interlock with Conservative Rasterizer
  - Better synchronization would help
- Merging artifacts

merge

![](_page_48_Figure_5.jpeg)

![](_page_48_Picture_6.jpeg)

![](_page_48_Picture_7.jpeg)

#### Limitation

- Rendering speed
  - Pixel Shader Interlock with Conservative Rasterizer
  - Better synchronization would help
- Merging artifacts

discard

![](_page_49_Figure_5.jpeg)

![](_page_49_Picture_6.jpeg)

#### Limitation

- Rendering speed
  - Pixel Shader Interlock with Conservative Rasterizer
  - Better synchronization would help
- Merging artifacts

**Z**-prepass

leak

![](_page_50_Figure_5.jpeg)

![](_page_50_Picture_6.jpeg)

#### Conclusion

- A streaming compression algorithm for geometric anti-aliasing
- Achieves close to 512x SS result with storage of 8x MSAA

- Decouple visibility into depth and coverage
  - Higher sample rates in reasonable memory footprint
  - Other applications
- Performance limitation

![](_page_51_Picture_7.jpeg)

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![](_page_52_Picture_8.jpeg)

# Thank you!

![](_page_53_Picture_1.jpeg)

![](_page_53_Picture_2.jpeg)